

# SPS Optics Measurements with Closed Orbits

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- ✿ Motivation
- ✿ Introduction : optics measurements  
& corrections.
- ✿ Optics measurement using closed orbits  
at the SPS.
- ✿ Optics measurement for the TI8 transfer line.
- ✿ Conclusions.

# Motivation

- A machine optics should match the model as closely as possible :  
orbit correction, knobs, aperture ...
- To achieve this :
  - ✓ The beam optics must be measured.
  - ✓ Deviations must be corrected !
- So far we made lots of measurements but seldom corrections  
LEP : only low-beta quadrupoles were adjusted – was sufficient !
- For LHC the situation might be more critical than for LEP and SPS  
→ we would like to have tools to correct a poor optics and identify the problems.

# Optics measurements I : K-modulation

The **local  $\beta$ -function** is determined by measuring the **tune change  $\Delta Q$**  due to a **change or modulation  $\Delta K$**  of the quadrupole strength  $K$  :

$$\Delta Q \propto \int_{Quad} \beta(s) \Delta K(s) ds$$

K-modulation was for example used at LEP to measure and correct  $\beta^*$  (in fact the  $\beta$  @ low-beta quadrupoles)

## Pro & contra :

- ✓ simple,  $\Delta Q$  can be measured with high accuracy.
- ✓ ~ fast.
- ✓ parasitic measurements during 'physics' possible.
- ✗ requires individual power converters or special windings.
- ✗ must know precisely the transfer function  $\Delta I \rightarrow \Delta K$ !

# Optics measurements II : phase advance

A (large) betatron oscillation is launched to measure the phase advance  $\Delta\mu$  between each pair of beam position monitors (BPM). The  $\beta$ -function at the BPMs can then be reconstructed from the phase advance (provided some assumptions are made) .

Widely used everywhere....

## Pro & contra :

- ✓ accurate (~ % on  $\beta$ ).
- ✓ fast.
- ✗ requires large amplitude oscillations (not so nice with protons...).
- ✗ does not work with lines.

# Optics measurements III : orbit response

The orbit or trajectory change (response) due to a steering magnet (corrector) kick  $\theta$  is measured with BPMs. The position change  $\Delta u_i$  @  $i^{\text{th}}$  monitor is related to a kick  $\theta_j$  @  $j^{\text{th}}$  corrector by :

$$\Delta u_i = R_{ij} \theta_j$$

**R = response matrix**

$$R_{ij} = \frac{\sqrt{\beta_i \beta_j} \cos(|\mu_i - \mu_j| - \pi Q)}{2 \sin(\pi Q)}$$

Closed orbit

$$R_{ij} = \begin{cases} \sqrt{\beta_i \beta_j} \sin(\mu_i - \mu_j) & \mu_i > \mu_j \\ 0 & \mu_i \leq \mu_j \end{cases}$$

Trajectory

## Pro & contra :

- ✓ simple & fast *qualitative* check.
- ✗ depends on BPM and corrector calibrations.
- ✗ de-convolution of  $\beta/\mu$  is not straightforward.

# Optics Corrections (I)

## ● 'Ideal' solution :

Throw all information on the measured  $\beta$ -functions into your favorite matching program (MAD...) and rematch the optics...



Not guaranteed to work...

## ● 'Linearization' :

Proceed by linearization of the model and iteration.

### 1) Evaluate the gradient :

Evaluate the local gradient of  $\beta/\mu$  with respect to a set of strengths  $k_1$  to  $k_n$ .

→ defines a matrix  $\mathbf{G}$

$\mathbf{G} = \mathbf{G}(k_i) \leftrightarrow$  valid over a limited range !

$$\mathbf{G} = \begin{pmatrix} \frac{\partial \beta_1}{\partial k_1} & \dots & \frac{\partial \beta_1}{\partial k_n} \\ \vdots & \ddots & \vdots \\ \frac{\partial \beta_m}{\partial k_1} & \dots & \frac{\partial \beta_m}{\partial k_n} \end{pmatrix}$$

# Optics Correction (II)

## 2) Least-square minimization :

Solve the following equation for strength changes  $\Delta k$

$$\| (\vec{\beta}^{meas} - \vec{\beta}^{model}) + \mathbf{G}\Delta\vec{k} \|^2 = \text{minimum}$$

This type of equation is solved routinely for orbit correction with least-square algorithms : SVD, MICADO..

## 3) Iterate until the minimum is stable :

- Update model with new strengths  $k_i \rightarrow k_i + \Delta k_i$
- Re-evaluate matrix  $\mathbf{G}$ .
- Find new least-square solution.
- ...

the problem is  
not linear !!!

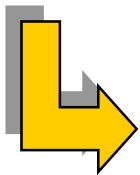


Hopefully you can re-match to model to fit  
the data  $\rightarrow$  know what's wrong !

# Optics Correction : the LOCO program

A program named **LOCO** was developed at BNL by J. Safranek to check and correct machine models, BPMs, orbit corrector magnets... for synchrotron light sources.

- Input data : the **orbit response matrix**  $R = (R_{ij})$
- LOCO proceeds by **linearization** and **least-square minimization**.
- It can handle BPM and corrector calibrations, corrector and BPM roll, coupling, ... in fact everything that can be parametrized.
- LOCO is '**loosely**' coupled to **MAD** (automatic script generation...).
- It has been **used** (apparently) **with success** in many US light sources.



LOCO was adapted and modified to run on the SPS and the LHC transfer lines → **for evaluation...**

**First test of LOCO on a 'large' machine.**



# Optics corrections with LOCO (I)

## 1) Measurements :

A vector holding the weighted difference between the measured and modeled response is build from all matrix elements :

$$r_k = \frac{R_{ij}^{meas} - R_{ij}^{mod}}{\sigma_i} \quad \forall i, j$$

$\sigma$  is the measurement error

## 2) Local gradient :

Evaluate the sensitivity wrt parameters  $c_1$  to  $c_n$  (BPM and corrector calibrations, strengths...)

$$\mathbf{G} = \begin{pmatrix} \frac{\partial r_1}{\partial c_1} & \dots & \frac{\partial r_1}{\partial c_n} \\ \vdots & \ddots & \vdots \\ \frac{\partial r_m}{\partial c_1} & \dots & \frac{\partial r_m}{\partial c_n} \end{pmatrix}$$

# Optics Correction with LOCO (II)


## 3) Least-square minimization :

Solve the equation for parameter changes  $\Delta c$

$$\| \vec{r} + \mathbf{G}\Delta\vec{c} \|^2 = \text{minimum}$$

## 4) Iteration :

Update  $c$ , update  $\mathbf{G}$ , solve again... until the solution is stable.


$$\| \vec{r} \|^2 = \sum_{i=1}^n r_k^2 = \text{minimum} \approx m - n \quad m = \# \text{ elements } R_{ij}$$

For 'gaussian' errors (and provided there are correctly estimated) the minimum value that can be achieved is well determined.  
Provides a statistical test of the fit quality.


# Matrix sizes...

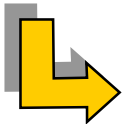
Consider a ring with **N** BPMs and **M** correctors per plane. The typical size of the gradient matrix **G** is :

$$(2 \times N \times M) \times (2 \times (N + M))$$

...with BPM and corrector calibration as parameters for c.

- **SPS** :  $N = 113$  ,  $M = 108$      $\sim 25000 \times 221$      $\rightarrow \sim 6 \cdot 10^6$  elements
- **LHC** :  $N = 500$  ,  $M = \sim 250$      $\sim 250000 \times 1500$      $\rightarrow 375 \cdot 10^6$  elements !!!

- 
- For LHC, one has to restrict to a fraction of the correctors / split the data. There is anyhow redundancy in the correctors (phases).
  - Or one has to assume that the BPM & corrector calibrations are known ...



Must be clever with large machines...

# LOCO test @ the SPS

Orbit response measurements the SPS :

- LHC type beams @ 66 GeV/c (during the ramp).
- Corrector kicks : +20 & -20  $\mu\text{rad}$  ( $\rightarrow \pm 2$  mm peak orbit changes).
- 18 (21) H (V) correctors were bumped in the sextants 1 & 2.
- Non-standard tunes ( $Q_x, Q_y$ ) = (26.76, 26.83).
- The phase advance between monitors in the SPS is (almost) 90°.

Since the  $\beta$ -beating 'runs' twice as fast as the orbit :

$$\Delta\beta(s) \propto \frac{\beta_0\beta(s) \cos(2|\mu(s) - \mu_0| - 2\pi Q)}{2 \sin(2\pi Q)}$$

- ✘  $\approx 180^\circ$  change between BPMs  $\rightarrow$  poor sampling !
- ✘ 90° lattices are not *ideal* for optics measurements (K-modulation is OK !).

# SPS model and fit parameters

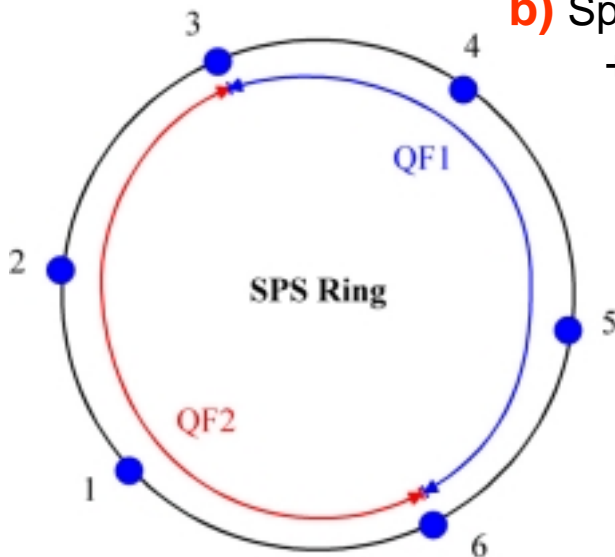
- Input model : nominal SPS model,  $(Q_x, Q_y) = (26.62, 26.58)$   
→ deliberate model error !

- Fit parameters :

- BPM and corrector calibrations.
- Main quadrupole strengths :

a) Use normal strengths for QF1, QF2 and QD  
→ 3 parameters, ~ simple tune adjustment.

b) Split the QF1, QF2 and QD chains into individual sextants  
+ free the strength of the large aperture quadrupoles.



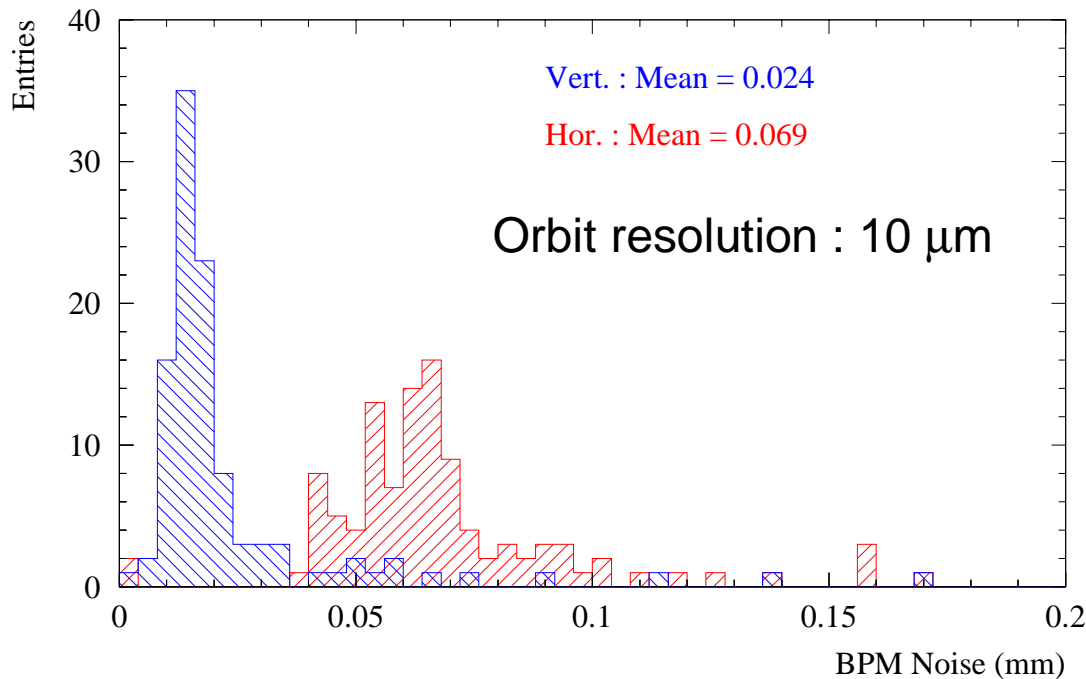
17 strength parameters

# Measurement noise

The **noise** (electronics, SPS reproducibility...) is estimated from the RMS position change of reference orbits acquired during the measurements :

- vertical plane ~ 24  $\mu\text{m}$
- horizontal plane ~ 70  $\mu\text{m}$

A ratio ~ 2 is expected for pure BPM noise (aperture)



More 'noise' may be introduced into the measurements by **BPM non-linearity** !

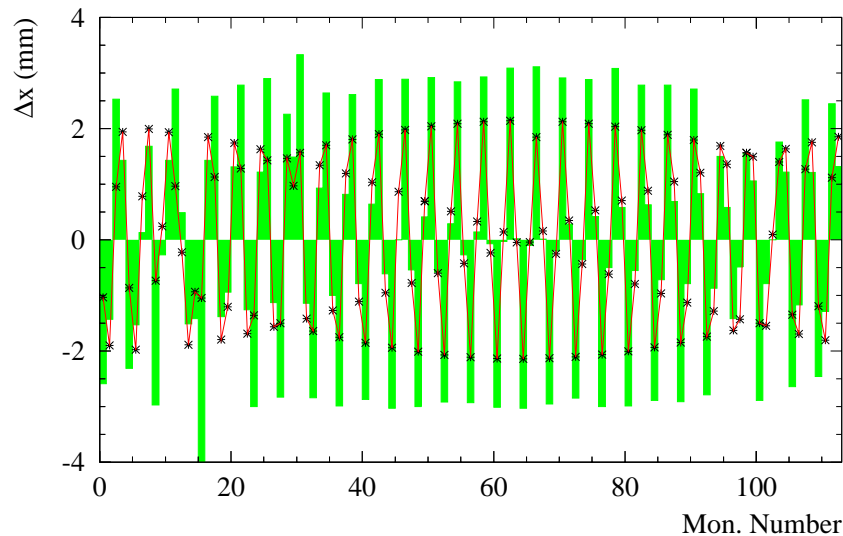
# Before fit : model versus data

An amplitude error is visible, due to the tune error & orbit factor  $\sin(\pi Q)$  :

$$\sin(26.6 \pi) / \sin(26.8 \pi) \sim 1.6$$

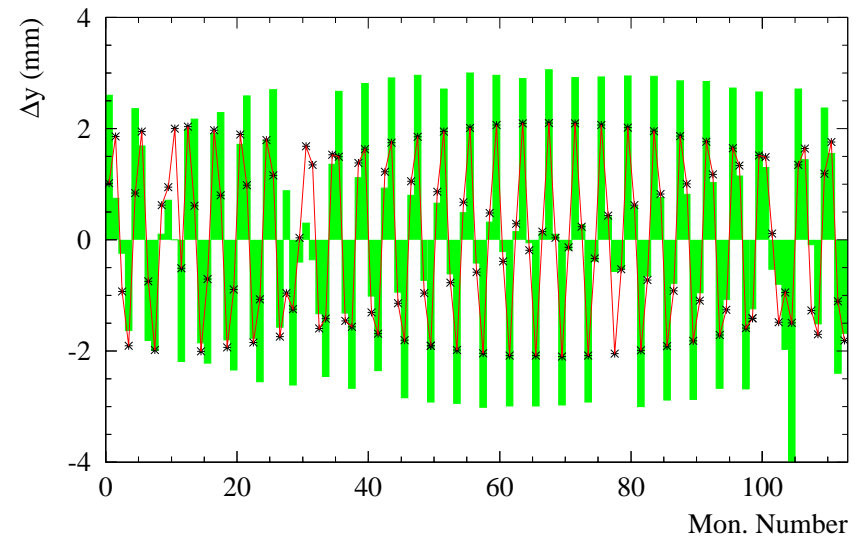
$$\Delta x / \Delta y = \text{response } \theta^+ - \text{response } \theta^-$$

Histogram : raw data



MDHD.118

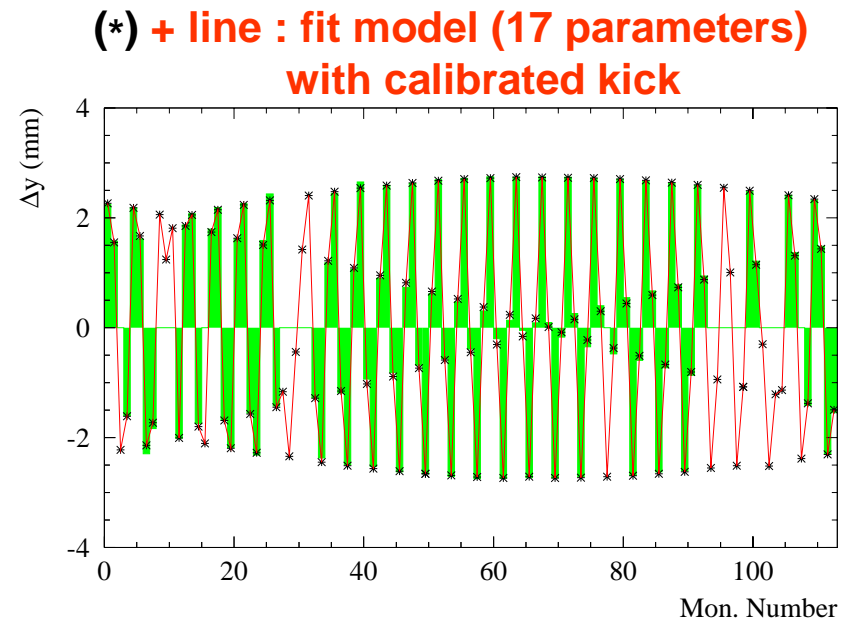
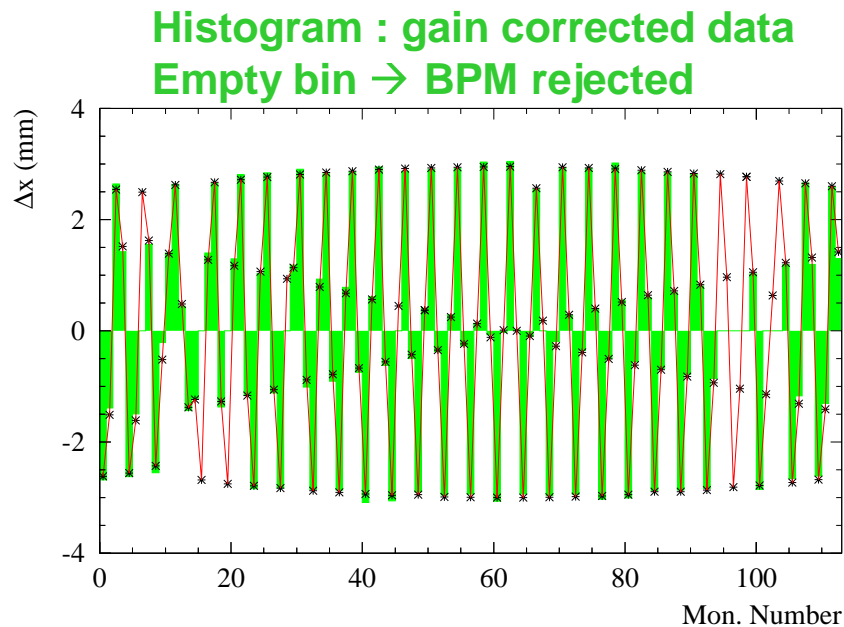
(\*) + line : model , tunes = (26.62,26.58)



MDV.121

## A few fit iterations later...

- ✓ BPM and correctors are calibrated.
- ✓ Fit model tunes = (26.762, 26.826) , exactly as expected !
- ✓ At first sight – excellent agreement model-data.
- ✓ Sextant-to-sextant strength modulation ~ 0.1-0.2%.



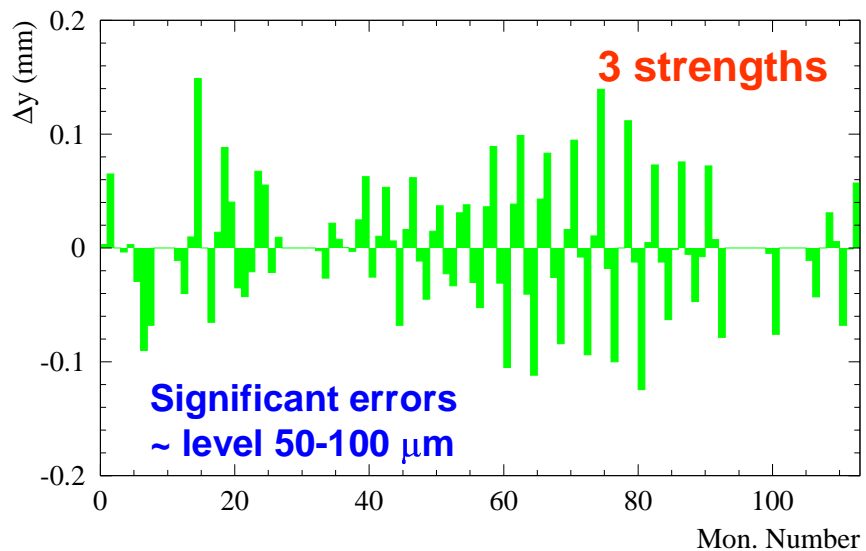


# Difference data-model

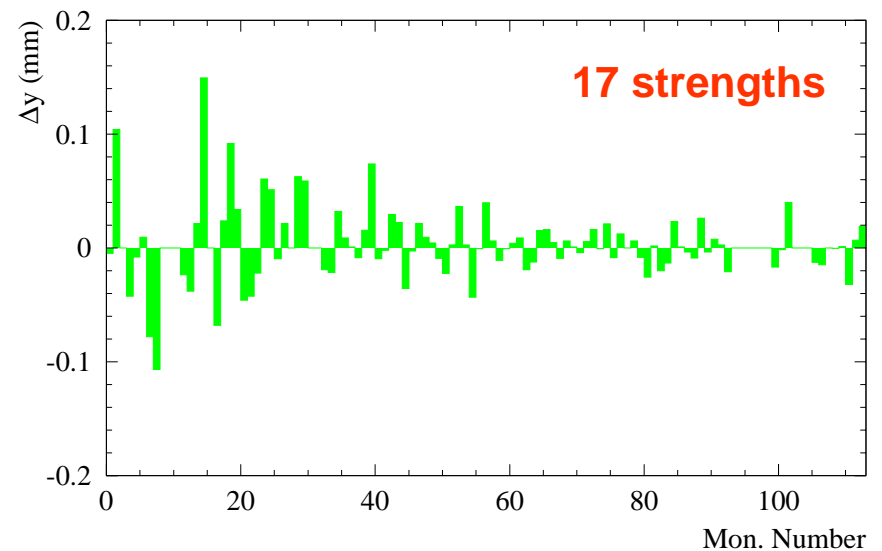
RMS difference data-fit model with 17 strengths :

- ➡ H plane  $\sim 90 \mu\text{m}$   $\rightarrow$  expect  $100 \mu\text{m}$
  - ➡ V plane  $\sim 44 \mu\text{m}$   $\rightarrow$  expect  $35 \mu\text{m}$
- $\approx$  at noise limit !

Histograms : calibrated data-fit model / V plane



MDV.205



MDV.205

# Calibration factors

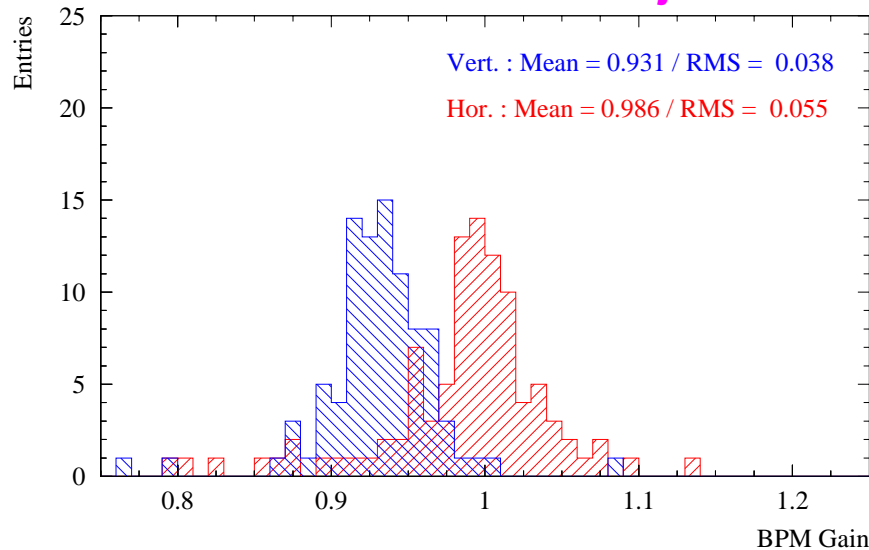
➡ H plane : **BPM gains (re)normalized to dispersion !**

Corrector gains : very low.

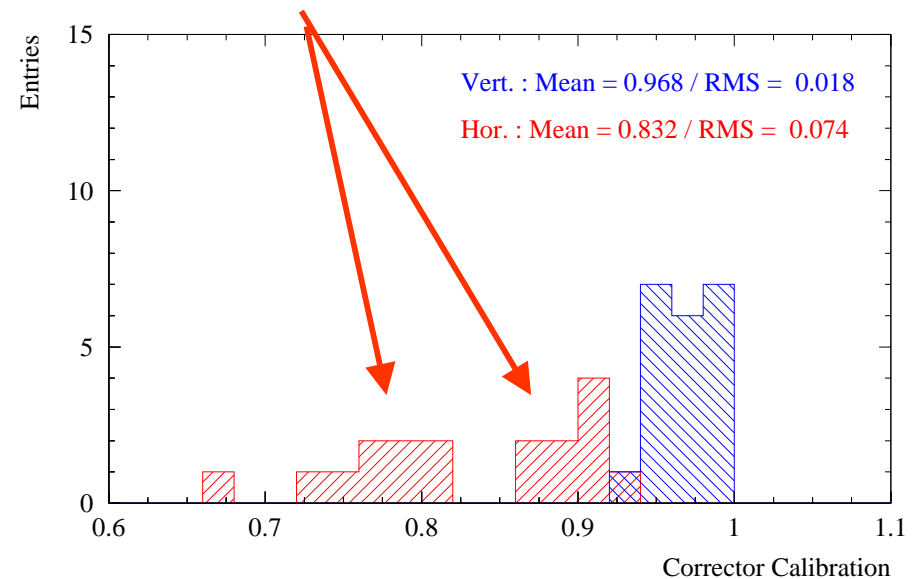
double peak  $\leftrightarrow$  correctors 90° out of phase.

➡ V plane : calibrations ~ OK.

**36 out of 226 monitors rejected !!**



**Suspicious double peak !**

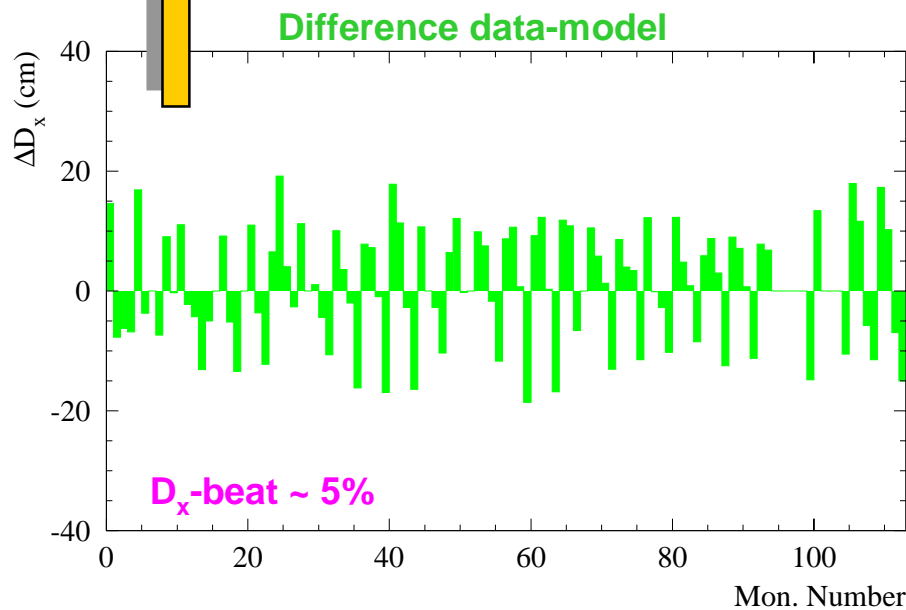


# Horizontal Dispersion

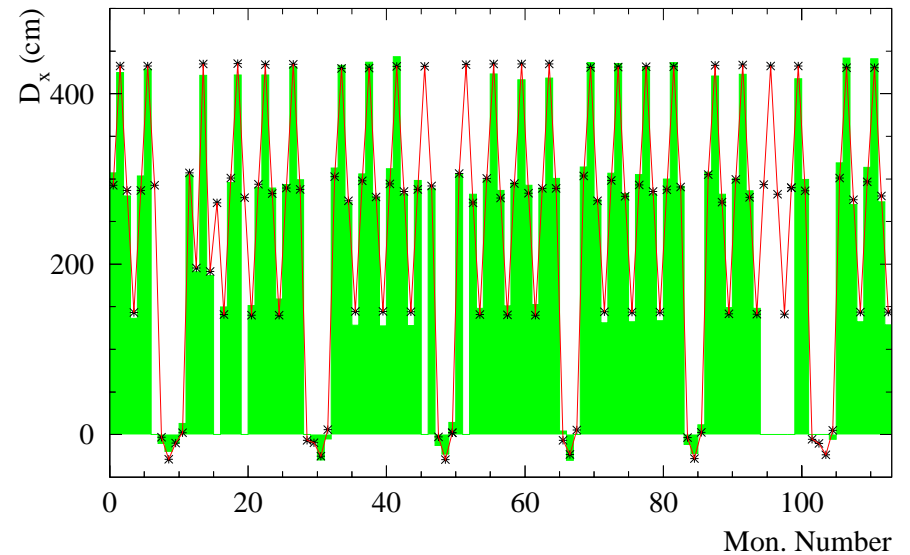
- Not included in the fit, since it also depends on the bending (errors).
- Can be used to check the model and set the BPM scale.



Can be explained by a horizontal  $\beta$ -beat of  $\sim 5$  to 10%.



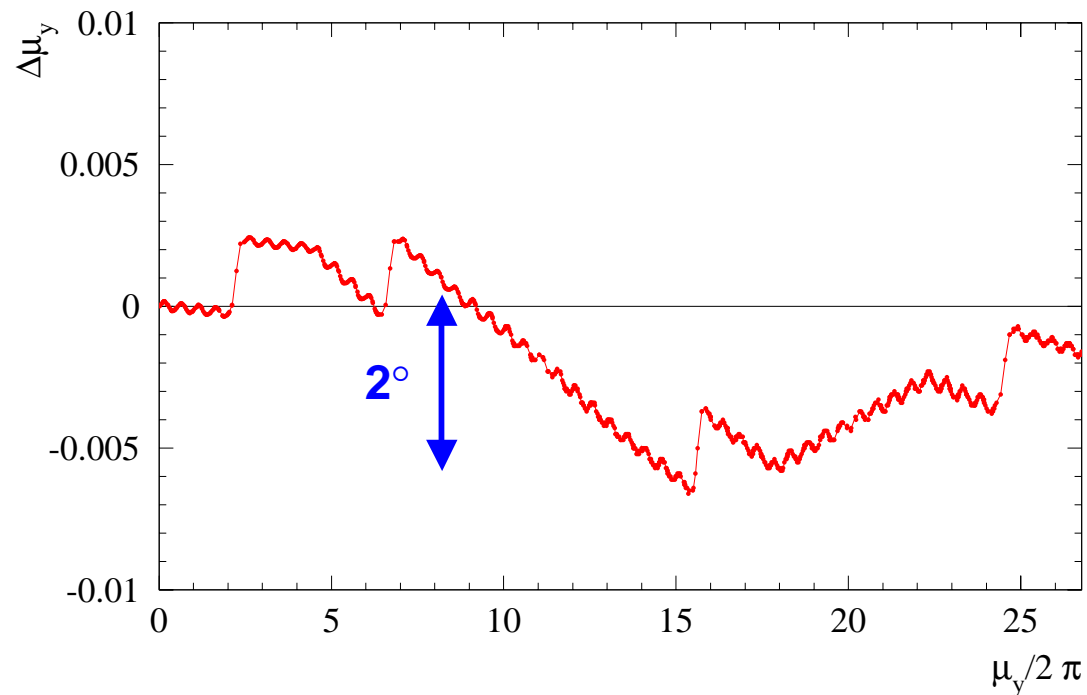
(\*) + line : fit model Histo : gain corrected data



# Model differences...

The main effect of the varying 17 strengths (versus 3) :

- A small phase advance 'modulation' over the ring.
- The associated  $\beta$  change is ~1-2 % !



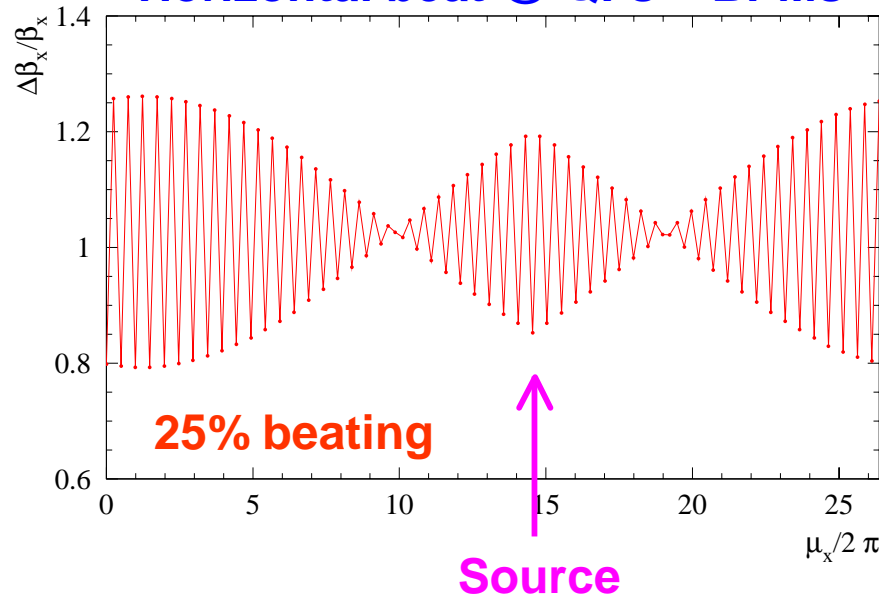
# Simulation with $\beta$ -beating

Can the fit absorb the  $\beta$ -beating signal in the BPM + corrector calibrations ?

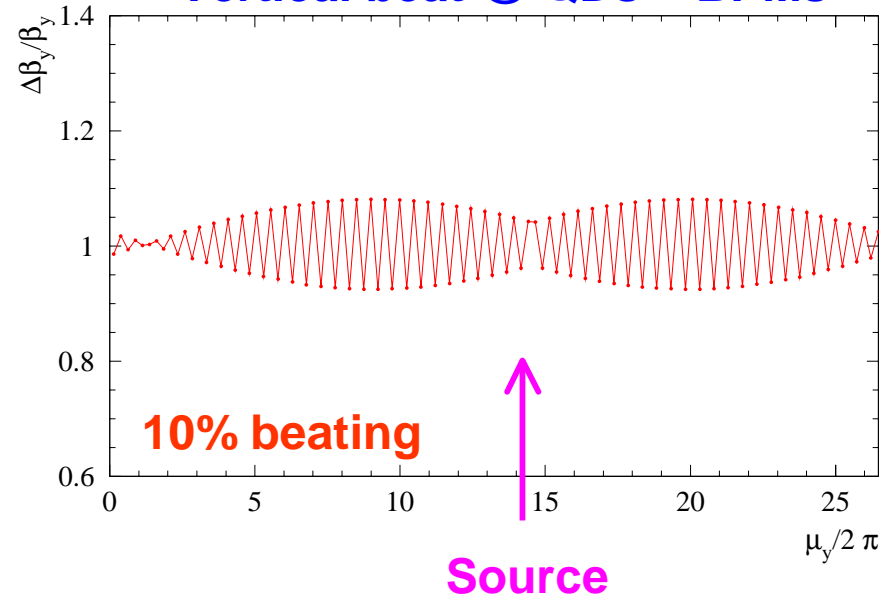
- 1 QF quadrupole mismatched.
- Fit with BPM & corr. calibrations, 17 strengths (same as for data) :  
↔ the fit cannot properly correct the  $\beta$ -beat (no 'access' to individual quads !).

**Amplitude modulation ↔ Sampling +  $\Delta\mu$ /cell not exactly  $90^\circ$**

**Horizontal beat @ QFs ~ BPMs**



**Vertical beat @ QDs ~ BPMs**

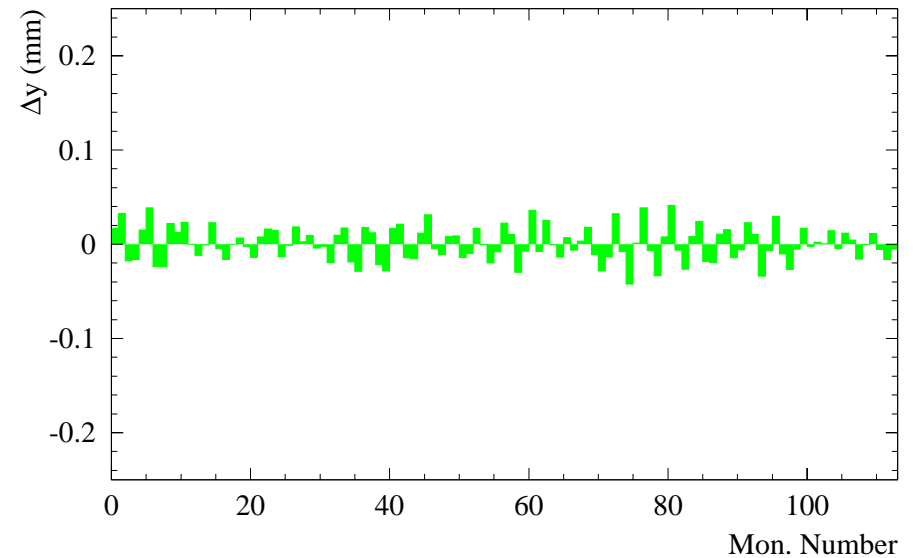
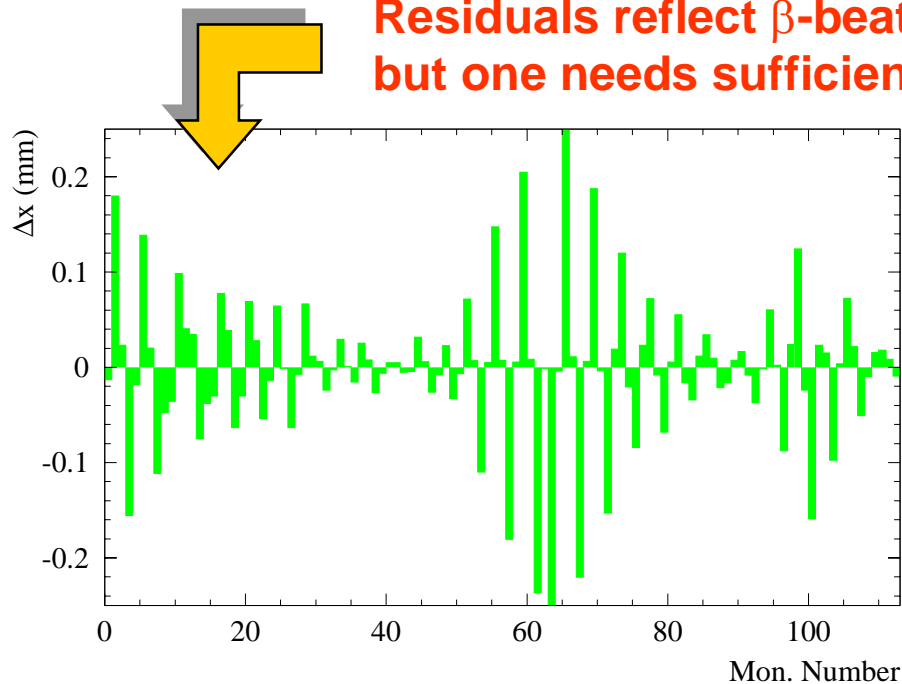


# After fit with $\beta$ -beating

Residual difference data – model :

- ➡ H plane  $85 \mu\text{m}$   $\approx$  similar to data
- ➡ V plane  $30 \mu\text{m}$  (10  $\mu\text{m}$  noise in the simulation)

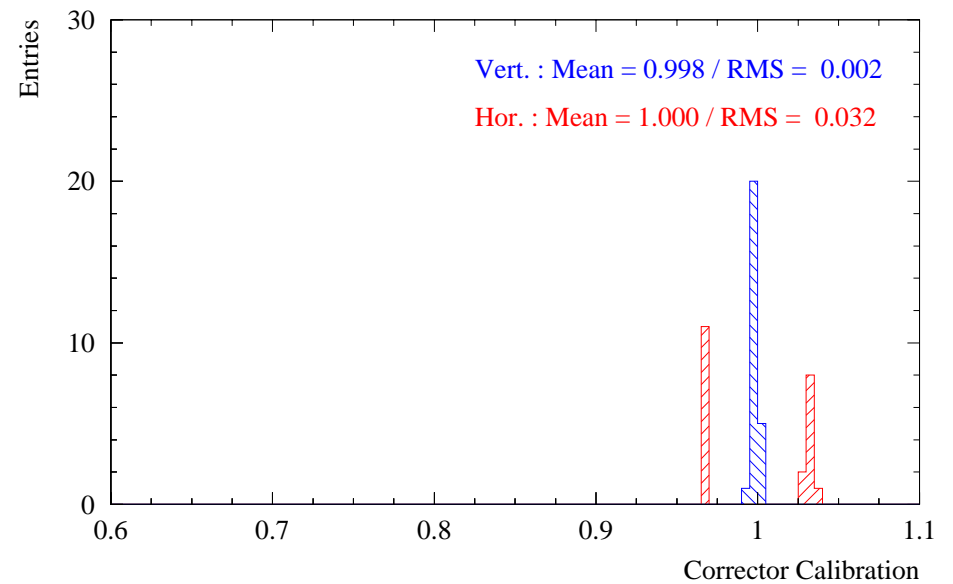
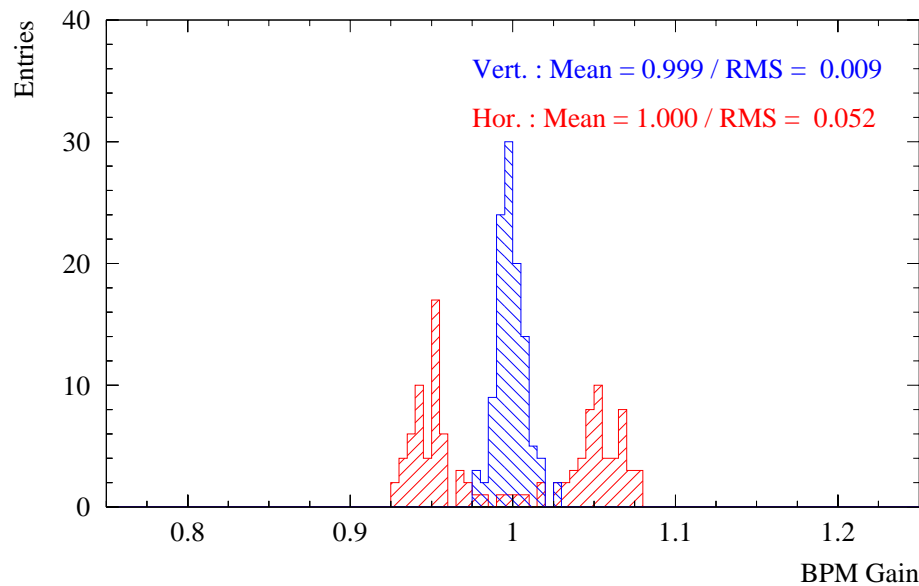
**Residuals reflect  $\beta$ -beat, but one needs sufficient resolution to see the structure !**



# Calibration factors with $\beta$ -beating

BPM & corrector calibrations :

- ➡ H plane    distinct 2 peak structure – similar to data for correctors.  
→ some beating ‘absorbed’ into calibration factors
- ➡ V plane    ~ nothing visible

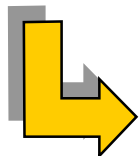


# Beating or no beating ?



The previous example shows that :

- A fit will always do its best, but if you don't give him the correct parameters, it can artificially 'squeeze' the other parameters.
- It is important to find / guess the error source, in which case LOCO works extremely well.
- The 90° phase advance (BPMs, corr., cell) makes life difficult : poor sampling, beating can be absorbed in calibration factors.
- ~ 10%  $\beta$ -beating could be hidden in the data, even if the fit looks good ! Some features require further studies.

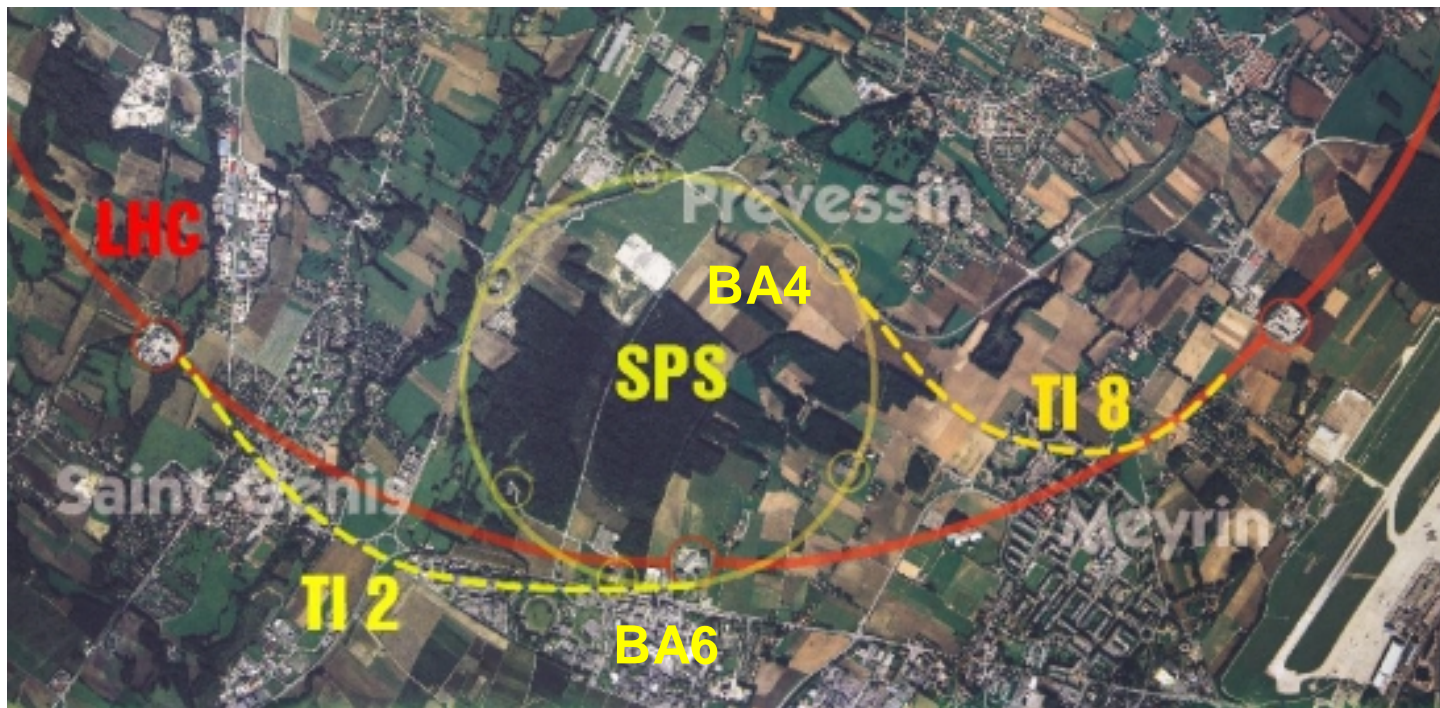


More studies and X-checks in 2002



# The LHC transfer lines

- The total length of TI2 + TI8 is equivalent to one SPS.
- The aperture of the lines is small.
- We must deliver a well-matched beam to the LHC ( $\epsilon$  budget).
  - The line optics is important (but not sufficient !).
  - Simulate LOCO on the TI8 line.



# TT40 & TI8 line

## Structure :

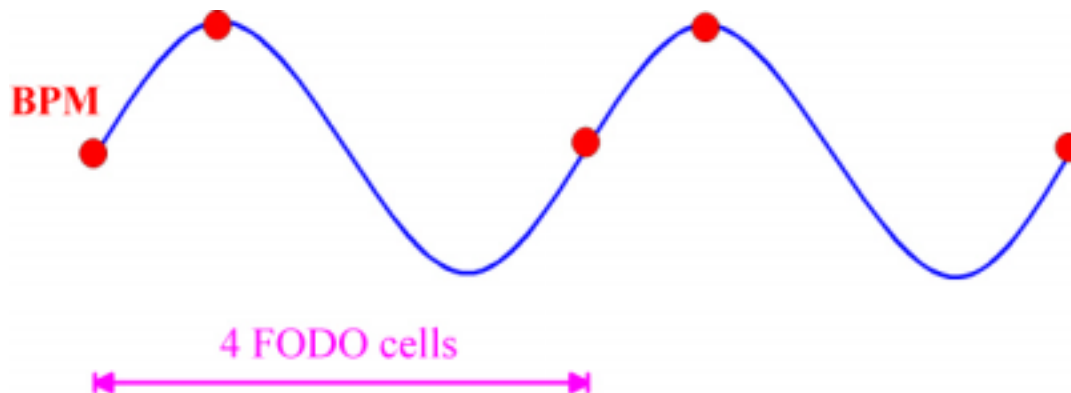
- matching sections at either ends.
- 85 half cells.

## **Problem areas for LOCO fits :** start & end of line

- **First BPM and last corrector cannot be calibrated** (both planes).
- **First & last 2 quadrupole strengths cannot be properly determined.**



insufficient sampling / too many degrees of freedom !



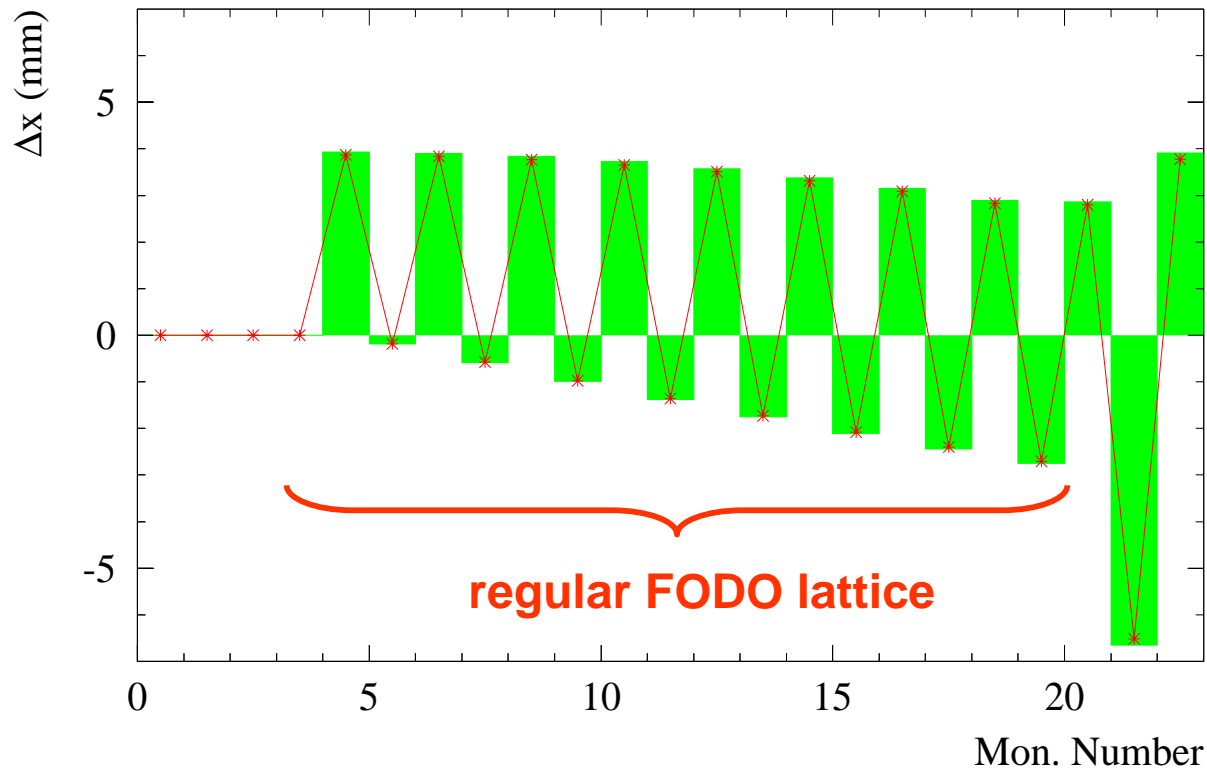
In the FODO cells, the BPM sampling is based on a 2-in-4cell layout (separate in each plane).



$\frac{1}{2}$  sampling of the SPS ring

# Trajectory response TT40 & TI8

Response to an upstream horizontal corrector kick ( $\pm 20 \mu\text{rad}$ ).



With a small phase advance error in the FODO lattice !

# Sensitivity test on TT40 & TI8

## A) Test conditions :

- nominal (perfect) optics.
- 5% BPM calibration errors.
- 1% corrector calibration errors.
- 50  $\mu\text{m}$  monitor noise + 50  $\mu\text{m}$  'other' noise (ripple)
- to improve the sampling (+50%) the profile monitors were added to BPMs (same errors & noise).
- FIT : **BPM & corr. calibrations and all possible quad strengths.**

## B) Test conditions : same as A) but

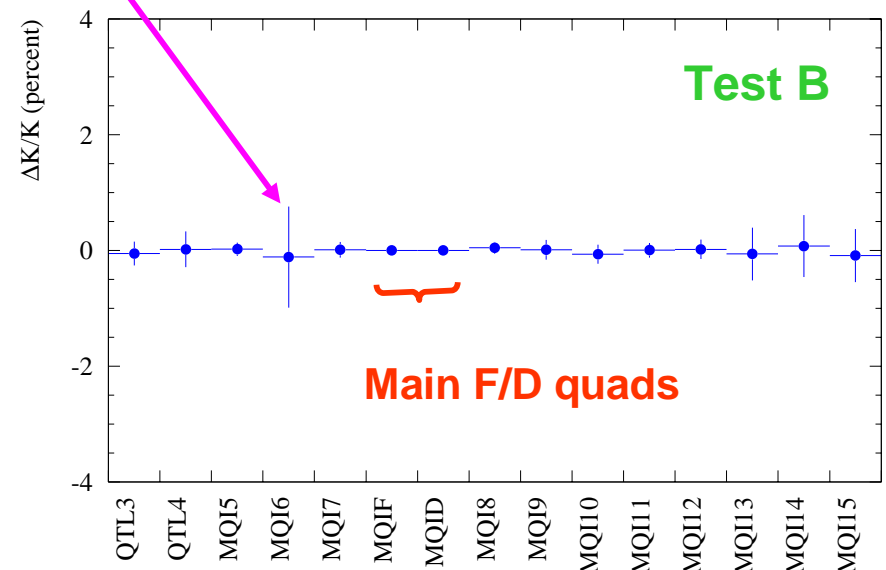
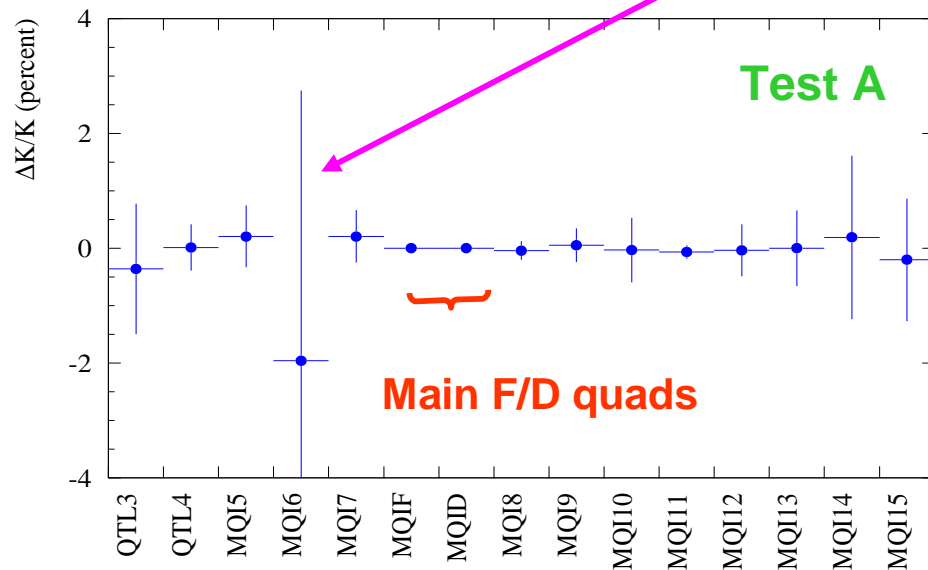
- 1% BPM calibration error, calibration fixed !
  - adds a small error/noise of  $\sim 20 \mu\text{m}$ .
- 0.1% corrector error, calibration fixed !
  - adds a negligible error !

What are the reconstructed quadrupole gradient errors under such conditions ?

# Reconstructed TT40/TI8 strengths

- Reconstructed strength errors → define the sensitivity !
- The errors are reduced significantly if the BPM scale is known...  
↔ # of degrees of freedom versus sampling in fit !

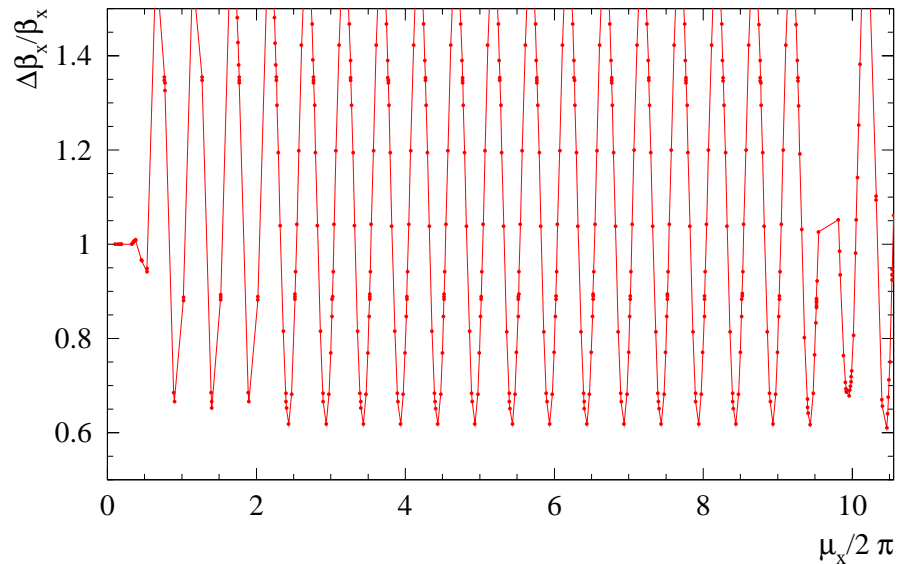
Unfavorable  $\Delta\mu$  with respect to upstream H corr.



# Corrected line optics

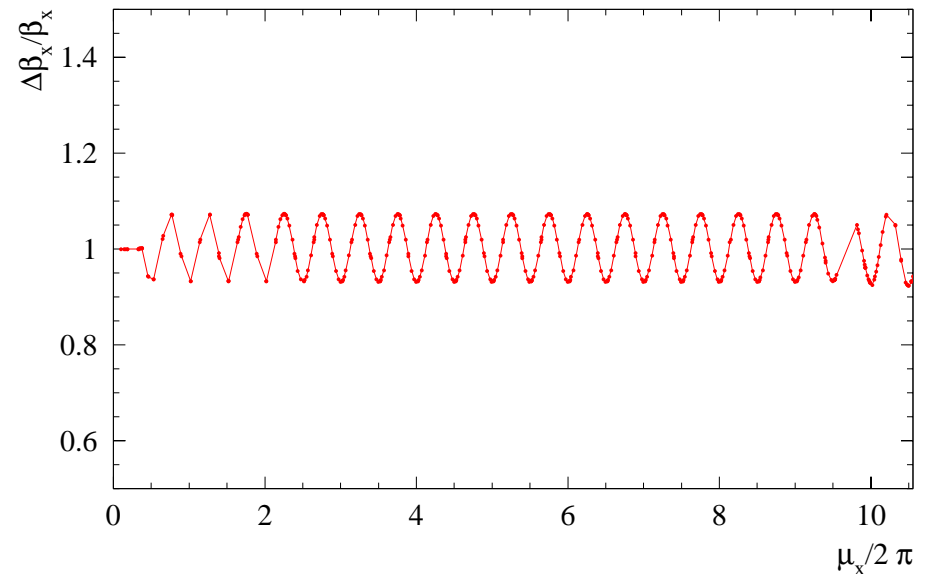
## Careless correction :

- MQI6 quad trimmed, ignoring the poor accuracy...
- Huge beating added (!! ) to a perfect line optics !



## Careful correction :

- Quads with poor accuracy ignored.
- Adds moderate beating  $\sim 5-10\%$   
↔ limit on  $\beta$ -beat correction due to measurement accuracy...



# Conclusions

## ✿ Orbit response - LOCO

- program was adapted and works well, although matrix sizes become large for SPS and LHC.
- provides calibration of monitors and correctors.
- interpretation of results can be delicate – particularly with phase advances close to 90°.

## ✿ SPS tests in 2002

- re-measure with more correctors, check stability of results.
- measurements with controlled  $\beta$ -beating.
- X-check with K-modulation (windings installed around some quads in point 5) and phase advance measurements.

## ✿ TI lines

- LOCO is very good for main (FODO) quads.
- At the limit for the matching quads with all parameters free !  
→ good BPM & corrector calibrations are an asset !